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2 3

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- 30
- 30 **Detailed geodetic imaging of earthquake rupture enhances our understanding of**
- 32 earthquake physics and induced ground shaking. The April 25, 2015 Mw 7.8 Gorkha,
- 33 Nepal earthquake is the first example of a large continental megathrust rupture
- 34 beneath a high-rate (5 Hz) GPS network. We use GPS and InSAR data to model the
- 35 earthquake rupture as a slip pulse of ~20 km width, ~6 s duration, and with peak
- 36 sliding velocity of 1.1 m/s that propagated toward Kathmandu basin at ~3.3 km/s
- 37 over ~140 km. The smooth slip onset, indicating a large ~5 m slip-weakening
- distance, caused moderate ground shaking at high >1Hz frequencies (~16% g) and
- 39 limited damage to regular dwellings. Whole basin resonance at 4-5 s period caused
- 40 collapse of tall structures, including cultural artifacts.
- 41
- 42 **One sentence summary:** High-rate GPS records reveal that the Gorkha earthquake
- 43 resulted from eastward propagation of a ~6s long slip pulse, with smooth onset which
- 44 generated mild ground shaking but exited resonance of Kathmandu basin at \sim 4-5 s.
- 45

The shape of the slip-rate time function (STF) during seismic rupture provides critical insight into constitutive fault properties. The abruptness of slip onset determines the high frequency content and hence the intensity of the near-field ground motion (1), whereas the tail, which discriminates pulse-like and crack-like ruptures (2), has a low frequency signature. Therefore, resolving the STF with band-limited strong motion records is difficult. The combination of high-rate GPS waveforms (3, 4), which capture both dynamic and permanent deformation, overcomes this limitation.

53 The April 25th 2015 M_w 7.8 Gorkha, Nepal earthquake resulted from unzipping of the 54 lower edge of the locked portion of the Main Himalayan Thrust (MHT) thrust fault, along 55 which the Himalayan wedge is thrust over India (5). The earthquake nucleated ~80 km 56 northwest of Kathmandu and ruptured a 140 km long segment of the fault (Figure 1A) with 57 a hypocentral depth of ~15 km and a dip angle of 7-12°(5, 6). The MHT accommodates the 58 majority of the convergence between India and southern Tibet with a rate between 17 and 59 21 mm/yr (7). For the 2015 event, which resulted in over 8,000 deaths, mostly in the 60 Kathmandu and adjacent districts. Mercali shaking intensities (MMI) reported by the National Society for Earthquake Technology (8) reached up to IX (violent) and exceeded VI 61 62 (strong) over a 170x40 km² area. Kathmandu has been struck by repeated earthquakes in 63 the past, with major destruction (MMI>X, extreme) in 1255, 1344, 1408, 1681, 1833 and 64 1934 (9-11). These earthquakes all occurred close to Kathmandu and have been assigned 65 magnitudes between Mw 7.5 and 8.4. Damages in the Kathmandu basin were probably 66 amplified by site effects during the Gorkha earthquake as happened with past events (12, 13). The basin is filled with 500-600 m of fluviolacustrine sediments resting on 67 68 metamorphic basement (14).

69 The damage to the most vulnerable vernacular dwellings in Kathmandu, which rarely 70 exceed 4 stories, was in fact much less than expected in view of the 2015 earthquake's 71 magnitude and its proximity to Kathmandu. By contrast, some taller structures were more 72 severely affected, such as the 60 m tall Dharahara tower which collapsed, but had partially 73 survived the Mw 8.1-8.4 1934 earthquake.. The 1934 event induced much more extensive 74 destruction to vernacular dwellings in Kathmandu than in 2015 (20% of the buildings in 75 Kathmandu were destroyed in 1934, less than 1% in 2015) (15). These observations reflect 76 the combined effects of the source characteristics and local geological conditions, in addition to evolution of building practices. 77

78 The 2015 Gorkha earthquake ruptured a subhorizontal portion of the MHT lying 79 directly beneath a network (16) of continuous GPS (cGPS) stations recording at a high rate 80 of 5 samples per second, and one accelerometer station (17) (Fig. 1A). In addition, surface 81 displacements were measured with interferometric synthetic aperture radar, InSAR, (18, 82 19) (fig. S1). While a number of recent earthquakes were documented with similar 83 techniques (20, 21), the Gorkha event is the first occurrence of a large continental thrust earthquake to be observed by high-rate cGPS stations at very close distances to and 84 completely encompassing the rupture area. The combination of these measurements 85 provide the opportunity to image the kinematics of the source process and the strong 86 87 ground motion that led to the particular pattern of structural damage observed during this 88 earthquake.

The records of seismic displacements and accelerations (Figs. 2 and S2) show southward motion of up to 2 m, with a rise time on the order of 6 seconds. The pulse is particularly clear at cGPS station KKN4 located on bedrock just north of Kathmandu and

92 only \sim 13 km above the fault. The displacement at this station started at about 25 s after the 93 onset of rupture, corresponding to 15 seconds after P-waves arrival time (Fig.2), and 94 reached its final static value by about 32 s, using the USGS origin time of radiated direct P 95 waves at 06:11:26.270 UTC (6). The records clearly indicate a pulse-like rupture (22) with 96 slip on any given portion of the fault occurring over a short fraction of the total \sim 70 s 97 duration of the earthquake source (5). Given the \sim 78 km distance of KKN4 to the epicenter, 98 the pulse must have propagated at \sim 3 km/s, a value consistent with waveform modeling 99 and back projection of high frequency seismic waves recorded at teleseismic distances (5). 100 Surface velocities reached values of ~ 0.7 m/s. The cGPS station NAST within Kathmandu 101 basin shows, in addition to the pulse seen at KKN4, strong oscillations of period of about 3-102 4 seconds lasting for \sim 20 s (Figs. 2 and 3A). The Gorkha earthquake must have excited a 103 resonance of the Kathmandu basin as a whole. The resonance is clearly shown in the 104 response spectra from these stations as well as from the accelerometer station KATNP (Fig 105 3G-I).

106 To retrieve the kinematics of the seismic rupture, we carried out a formal inversion of 107 time-dependent slip on the fault (23, 24) and compared the recorded waveforms with 108 forward predictions assuming a propagating slip pulse with varied characteristics. We 109 assumed a planar fault geometry with a strike of 295° and a dip of 11° in accordance with 110 the teleseismic W-phase moment tensor solution from the USGS (6). We tested shallower dips up to 7° but found that 11° provided a better fit to the data. The fault was discretized 111 112 into 10x10 km subfault segments. We jointly inverted the three-component, 5 Hz GPS 113 derived velocity waveforms, the GPS static offsets, and the InSAR line of sight (LOS) static displacements measured between February 22 and May 3 (fig. S1). The GPS displacement 114 115 time series shows large postseismic motion at only one station (CHLM) with less than 2 cm 116 magnitude on both the horizontal and vertical over the week following the earthquake. 117 Therefore, for our purposes, we neglect the contribution of postseismic deformation to the 118 LOS displacements.. The model fits both data sets closely (Figs. 1A), with 86% variance 119 reduction for the InSAR and GPS coseismic displacements and 74% variance reduction for 120 the GPS velocity waveforms (Figs. S2, S4). The model indicates predominantly unilateral 121 rupture to the southeast with peak slip of ~ 6.5 m on a large asperity to the north of 122 Kathmandu. The event duration is 65 s (fig. S4) with peak moment release at 23 s when the 123 slip pulse is less than 10 km north of Kathmandu (movie S1), and peak slip-rate is 1.1 m/s. 124 Most of the slip is concentrated within a narrow region between the 10 and 20 km fault 125 depth contours. We find a large asperity with 3.0 m of slip due east of the main asperity and 126 between 20 and 23 km depth. The rupture velocity of the propagating slip pulse indicated 127 by the onset of slip in our best-fitting model is \sim 3.2 km/s and has a maximum allowed 128 velocity of 3.3 km/s (fig. S4). This velocity corresponds to ~95% of the shear wave speed at 129 the depth of the majority of slip (15 km) according to the local velocity model used to 130 calculate the Green's functions (Table S2), indicating a very fast rupture propagation. Slip 131 tapers at 17-20 km depth along the edge of the locked zone of the MHT. The inversion has a 132 large number of parameters, which allows for a relatively complex rupture history. 133 However, the resulting model is remarkably simple with essentially a single propagating 134 slip pulse. The spatio-temporal evolution of the slip pulse matches well the location of the 135 sources of high frequency (0.5-2Hz) seismic waves derived from the back projection of the 136 teleseismic waveforms (5) (Movie S1).

We calculated the static stress change on the fault plane due to the earthquake (Fig. 1B). It shows loading of the fault around the main asperity where most of the aftershocks occurred, including the Mw 7.3 aftershock of May 12, as expected from triggering by coseismic stress transfer (25). The model predicts a pattern of uplift of the Kathmandu basin and subsidence at the front of the high range (fig. S4), approximately opposite to the pattern observed in the interseismic period as expected from simple models of the seismic cycle on the MHT (26, 27).

144 The record at station KKN4 should be a close representation of the slip-rate time 145 function as it lies only about 13 km above the propagating slip pulse and is not affected by 146 the site effects seen at the stations in Kathmandu basin. We conducted synthetic tests with 147 the same Earth structure model used in the inversion (Table S1) to assess the distortion 148 and smoothing introduced by the elastic half space response (fig. S5). We found a vertical 149 velocity amplitude of about 70% of the peak slip rate on the fault directly beneath it along 150 with a well-preserved temporal shape. Furthermore, the tests demonstrate that the smooth 151 onset of slip is not an artifact resulting from the transfer through the elastic medium 152 represented by the elastodynamic Green's functions. The shape of the slip pulse can also be 153 retrieved from the GPS records at NAST and strong motion vertical records at KATNP 154 which are less affected by site effects than the horizontal records (Fig. 1). All three records 155 indicate a ~ 6 s duration pulse. The shape of the pulse fits the regularized Yoffe function 156 (28) yielding a rather smooth rise, with an acceleration time to peak slip rate of τ_s =1.7 s, a rise time of τ_R =3.3 s and a total effective duration of τ_{eff} =6.7 s. The slip-rate pulse derived 157 from the inversion is also well fit using the same values of τ_s and τ_R s and peak slip-rate of 158 159 \sim 0.9 m/s (Fig. 4). We compared the recorded waveforms with predictions from a suite of 160 forward models to test the robustness of our results. We used the static slip model in these 161 tests deduced from the inversion of the GPS static and InSAR measurements (Fig. S7). We 162 assumed a propagating slip pulse with varying characteristics using the regularized Yoffe 163 STF. We varied the rupture velocity between 2.8 and 3.6 km/s, and the rise time between 2 164 and 10s (fig. S8). We also tested the resolution power of the inversion and the limited bias 165 introduced by the regularization applied to the inversions by inverting synthetics 166 calculated from forward modeling (24, fig. S10, fig. S11). Together, these tests demonstrate 167 the duration of the slip pulse is probably less than 10 s and the time to the peak-slip rate 168 cannot be shorter than 1 s (we would otherwise observe a much larger amplitude at high 169 frequencies) and the average propagation rate of the slip pulse is not less than ~ 3.0 km/s 170 over the first 30 s (until KKN4, NAST and KATNP records a pulse signal).

171 Tinti et al (28) analyzed how the shape of the STF relate to the characteristics of the 172 friction law governing the dynamics of the rupture. Based on this rationale (their equations 173 6 and 11), we estimate the slip-weakening distance to be \sim 5 m (for a peak-slip of 6.5 m). 174 The distance is a large value compared to those estimated from kinematic and dynamic 175 modeling of seismic ruptures (29, 30), which tend to be overestimated (1) and are typically 176 on the order of 0.5 to 1 m. The large value we obtained is possibly related to the earthquake 177 occurring close to the brittle-ductile transition at the lower edge of the locked portion of 178 the MHT. The modeled smooth onset of the STF and the related large slip-weakening 179 distance provide an explanation of the relatively low amplitude of shaking at frequencies 180 above 1 Hz. The observed slip-weakening behavior does not require the friction law to be 181 actually slip-weakening. A fault obeying rate and state friction can show an effective slipweakening behavior with an effective critical distance several orders of magnitude larger
that the critical distance entering the friction law (*31*). Aspects of the rupture kinematics
and ground strong motion observed during the Gorkha event may also be due to hanging
wall effects, the importance of which could be assessed through dynamic modeling of the
rupture (*32, 33*).

187 Our study provides insight into the main factors that determined damage sustained 188 during the Gorkha earthquake. While the hypocenter was ~ 80 km away from the city, the 189 main asperity that radiated most of the energy was much closer, just north of the basin and 190 at relatively shallow depth. Comparison of the waveforms recorded within the sedimentary 191 basin at NAST and KATNP (fig. 3) with the bedrock records at KKN4 shows prominent 192 differences even though the stations are less than 13 km apart. The waveforms at the 193 bedrock station KKN4 are simple, mostly dominated by the single pulse, while within the 194 basin peak horizontal ground velocities of 0.5 to 0.8 m/s (considered severe to violent, 195 (34)) are sustained for 20 s at KATNP and 40 s at NAST. The ratio of the amplitude spectra 196 of the basin waveforms to those at the hill station (Fig. 2D-F) shows amplification of long 197 period energy between 1 and 9 s with the basin amplitudes being 6-7 times larger in the 198 horizontal direction than at the bedrock station. The response spectra (Fig. 2G-I) show that, 199 within this amplified period band, it was the 4 s period shaking that was the strongest at 200 the basin stations.

201 The 4 s peak in the response spectra coincides with the observation that the source 202 time function beneath Kathmandu likely had a duration of \sim 6-7 s. The net effect of this long 203 source duration with slow onset time is to produce radiation that is depleted of high 204 frequency energy (fig. S11). This explains why vernacular dwellings with only a few stories 205 were not severely affected despite the anticipated short period site effects from 206 microzoning (13). Furthermore, high frequency intensity measurements such as peak 207 ground accelerations were modest (Fig 2, $\sim 1.6 \text{ m/s}^2$, MMI VI), while longer period intensity 208 measures such as peak ground velocity (Fig 3) were very large (80 cm/s, MMI IX). 209 Kathmandu was faced with a combination of source and site effects. Rupture directivity 210 focused radiated seismic energy towards the city; the smooth onset and 6-7 second 211 duration of the pulse excited a resonance of the Kathmandu basin, producing protracted 212 duration of violent shaking at a period around 4s.

213

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239	processing and wrote the article. John Galetzka led the field operations. Jianghui Geng	
240	conducted the high rate data processing. Sue Owen, Angelyn Moore, Walter Szeliga and Jeff	
241	Genric	ch conducted the low rate data analysis to estimate co-seismic offsets. Eric Lindsey and
242	Xiaohi	a Xu conducted the InSAR data processing. Lok Bijaya helped organizing the field
243	operati	ions. All other authors contributed to building and servicing the GPS stations and to the
244	post-earthquake data recovery. All authors edited the article.	
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356 357 Figure 1: Cumulative slip distribution and static stress drop due to the Gorkha earthquake. (A) Slip inversion results for the Mw7.8 Gorkha event. The red star is the 358 359 hypocenter. Dashed contours are depths to the fault. Orange diamonds are 5 Hz cGPS 360 stations and white diamonds are low rate (1/30 Hz) stations. The green triangle is the 361 strong motion station. Kathmandu is represented by the blue square. The black arrows

indicate the coseismic offsets measured at the sites (the values and uncertainties are given
 in Table S1). Vectors with less than 10cm displacement are not shown (B) Static stress
 drop predicted by the model of figure 1A. Green circles are aftershocks with local
 magnitude >4 recorded and located by the Nepal National Seismic Center. Focal
 mechanisms represent the GCMT moment tensors for aftershocks with magnitude larger
 than 6.

368 369





Figure 2: Records of ground displacements and accelerations during the Gorkha
earthquake. Displacement waveforms at cGPS stations KKN4 and NAST (5 samples per
second) and acceleration waveforms at strong motion station KATNP (figure 1).





Figure 3: Evidence for resonance of Kathmandu basin. (A)-(C) three components of
ground velocity observed at two high-rate GPS stations (KKN4 and NAST) and one strong
motion station (KATNP) in the Kathmandu region. KKN4 is located on hard rock northwest

of Kathmandu while the other 2 stations are on soft sediment in the basin. The GPS is differentiated to velocity and the strong motion integrated after high-pass filtering at 0.02 Hz. (D)-(F) Ground motion amplification observed at the two basin stations. Plotted is the ratio of the amplitude spectra of the basin stations to the amplitude spectra of the reference bedrock station KKN4. (G)-(I) 5% damped velocity response spectra for all 3 stations. (J) Close up map showing the location of the basin and bedrock stations.







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